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Chapter 10: Sterilization and Bioreactor Operation

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Similarity (geometry) - Wikipedia

Chapter 5 expands our investigation of kinematics to velocities and static forces. In Chapter 6, we deal for the first time with the forces and moments required to cause motion of a manipulator. This is the problem of manipulator dynamics. Chapter 7 is concerned with describing motions of the manipulator in terms of trajectories through space.

Introduction to Robotics

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Geometry - Wikipedia

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